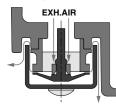
# **Electro-Pneumatic Positioner/Smart Positioner** (Lever type/Rotary type)

# Dustproof / Waterproof

Passed by external organization on JIS F8007 (conforms to IEC 60529) IP65



A centralized exhaust system employs the combination of the check valve and the labyrinth effect enhancing both dustproof and waterproof performance.

# Monitoring function

#### Electro-Pneumatic Positioner

· Opening current transmission analog (4 to 20 mA DC) continuous output

#### **Smart Positioner**

- · Alarm point output function (2 points)
- · Analog (4 to 20 mA DC) continuous output

## With external scale plate (Rotary type, Bottom mounting)



External scale plate

Improved visibility of opening indicator

# Explosion-proof construction

Electro-Pneumatic	TIIS explosion-proof construction (Exd II BT5)
Positioner	ATEX intrinsically safe explosion-proof construction ( II 2G Ex ib II CT5/T6 Gb)
Smart Positioner	ATEX intrinsically safe explosion-proof construction ( II 1G Ex ia II CT4/T5/T6 Ga)

# With internal opening indicator plate



Internal opening indicator plate

Opening indicator plate inside body

# **Body with LCD window**

(Smart Positioner)



#### **Electro-Pneumatic Positioner**

Universal mechanically controlled type



# Smart Positioner

Electronically controlled easy-adjustment transmitting type IP8001/8101 Series



# **Smart Positioner**

IP8001/8101 Series

# Built-in microcomputer and sensor allows easy remote parameter change and monitoring.



IP8101(Rotary type)

- Internal push button for easy setting of various parameters (Refer to parameter list)
- · Zero point/span adjustment easier than with previous mechanical positioners

Parameter List				
Notes	Parameter	Description		
	Positive operation/ reverse operation setting	Change operation direction with regard to input signal Change to internal components, piping not possible		
	Split range setting	Change range of input signal		
	Preferred zero point/span adjustment setting	Change actuator stroke range with regard to input signal		
	Forced full close/full open setting	To ensure valve closure, force actuator opening to be 0% or 100% with a preferred input signal.		
Standard equipped functions	Valve characteristic setting	Select from these 6 valve characteristics Linear characteristic Equality % characteristic (2 kinds) Quick open characteristic (2 kinds) User preferred point setting (11 points)		
	PID constant setting	Change PID constant		
	Calibration setting	Zero point/span adjustment, Auto PID constant setting, input signal display value calibration, etc.		
	Alarm 1 output setting	Set upper/lower stroke limits for actuator from which alarm is		
Optional	Alarm 2 output setting	output		
equipped functions	Analog (4 to 20 mA DC) output setting	Set increase/decrease direction for 4 to 20 mA DC output with regard to actuator stroke		

# **Full Output Functions**

Selecting models with output functions by model selection selects with alarm point output function (2 points) and analog (4 to 20 mA DC) continuous output function. This will allow remote detection of operating abnormalities.

# **Control State Display**

Positioning, deviation, and input value are displayed (numerically) on the internal LCD, allowing visual verification of the control state.



#### Display example

Positioning (%)

Input value (%)

Deviation (%)

# Handles 2-line Input for Current Equipment

Control furnished with current 2-line input signal (4 to 20 mA DC) not requiring separate power source.

## **HART Transmission Function**

HART transmission function can be designated by model selection.

Allows remote monitoring and setting change of positioner.

## Intercompatible Installation

Dimensions of mounting parts same as previous mechanical IP6000/IP8000 series Electro-Pneumatic Positioner. External feedback lever and fork lever-type fitting for joining actuator and positioner are therefore also the same.

# **Energy Saving Product**

Lever-type features 60% reduced air flow consumption compared with IP8000.

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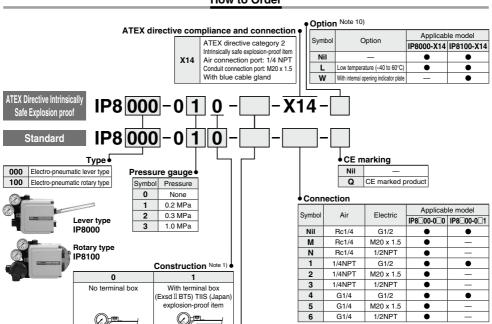
# Electro-Pneumatic Positioner (Lever type/Rotary type)

# (E

# IP8000/8100 Series

- Enclosure: JISF8007 IP65 (conforms to IEC 60529)
- Monitoring function (Opening current transmission 4 to 20 mA DC, Accessory J, JR)
- Explosion-proof construction/Electro-pneumatic positioner: TIIS explosion-proof construction (Exd II BT5), ATEX intrinsically safe explosion-proof construction (II 2G Ex ib II CT5/T6 Gb)

#### How to Order



Note 1) For construction No.1(with terminal box), the ambient and fluid temperatures are as follows:

- Exd II BT5 −20 to 60°C
- $\bullet$  Non-explosion proof (non hazardous locations only) –20 to 80°C The positioner body is EXd II BT5 labeled.

Note 2) If two or more accessories are required, the part numbers should be made according to alphabetical order. (ex. IP8100-010-AG)

Note 3) "A" is applied to approx 90cm3-capacity actuator.

- "B" is applied to approx 90cm³-capacity actuator.
  "B" is applied to approx 180cm³-capacity actuator.
- Note 4) Fork lever-type fitting MX (Connection thread: M6 x 1) for IP8100-0□0-□-X14. Note 5) Fork lever-type fitting SX (Connection thread: M6 x 1) for IP8100-0□0-□-X14.

Note 6) Standard lever is not attached.

- Note 7) It is to be used together with "A" or "B" when tending to overshoot by the use of "A" or "B".
  - It is mounted to the body as a replacement of the standard compensation spring.
- Note 8) For side mounting, select a model with internal opening indicator plate (IP8100-0□□-\-\-\-X318 for standard type, X14-W for ATEX intrinsically safe explosion-proof type).
- Note 9) Symbol J/JR is with terminal box, non-explosion proof specification. Select 1 for Construction. Positive operation signifies clockwise rotational direction by the main actuator shaft when positioner cover is viewed from the front.

Note 10) Combination of L and W is not available.

Accessories Note 2) Applicable model Symbol Accessories IP8000 IP8100 None (Standard) ø0.7 Output restriction with pilot valve Note 3) ø1.0 Output restriction with pilot valve Note 3) Fork lever-type fitting M Note 4) C Fork lever-type fitting S Note 5) D Е For stroke 35 to 100 mm with lever unit Note 6 For stroke 50 to 140 mm with lever unit Note 6) G Compensation spring (A) Note 7) With external scale plate Note 8) н • With opening current transmission (4 to 20 mA DC)/Positive operation Note 9 With opening current transmission (4 to 20 mA DC))/Reverse operation Note 9)

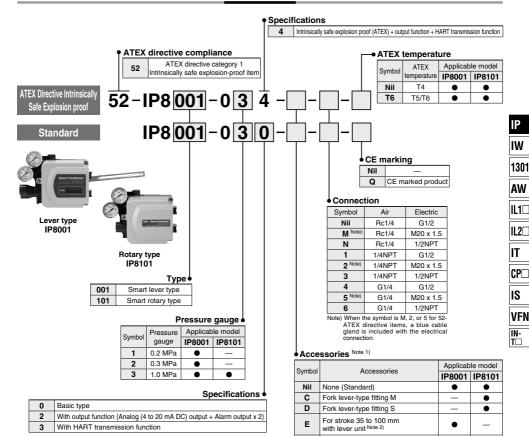
# **Smart Positioner** (Lever type/Rotary type)

# IP8001/8101 Series

Auto calibration

- HART transmission function
- Enclosure: JISF8007 IP65(conforms to IEC 60529)
  - Monitoring function
- Explosion-proof construction/ATEX intrinsically safe explosion-proof construction ( II 1G Ex ia II CT4/T5/T6 Ga)

#### How to Order



Body with LCD window Note 1) If two or more accessories are required, the part numbers should be given in alphabetical order. (ex. IP8101-010-CH)

Note 2) Standard lever is not attached. Note 3) For side mounting, select "-W" and check the control position by viewing the LCD display value.

For stroke 50 to 140 mm

With external scale plate Note 3)

with lever unit Note 2)

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#### Specifications Note 1)

Туре	IP8000	IP8100	IP8001	IP8101
	Electro-Pneumatic Positioner		Smart Positioner	
	Lever type lever feedback	Rotary type cam feedback	Lever type	Rotary type
Item	Single action Double action	Single action Double action	Single action /	Double action
Input current		4 to 20 mA DC	(Standard) Note 2)	
Min. operating current — 3.85 mA DC or more				C or more
Intra-terminal voltage		_	12 V DC (equivalent to 600 Ω i	nput resistance, at 20 mA DC)
Max. supplied power		_	1 W (Imax: 100 mA I	DC, Vmax: 28 V DC)
Input resistance	235 ±15 Ω (4	1 to 20 mA DC)	_	_
Supply air pressure		0.14 to 0.7 MPa		0.3 to 0.7 MPa
Standard stroke	10 to 85 mm (Allowable deflection angle 10 to 30	60 to 100° Note 3)	10 to 85 mm (Allowable deflection angle 10 to 30°)	60 to 100° Note 3)
Sensitivity Note 4)	Within 0.1% F.S.	Within 0.5% F.S.	Within 0.	.2% F.S.
Linearity Note 4)	Within ±1% F.S.	Within ±2% F.S.	Within ±	1% F.S.
Hysteresis Note 4)	Within 0.75% F.S.	Within 1% F.S.	Within 0.	.5% F.S.
Repeatability Note 4)		Within ±0	0.5% F.S.	
Coefficient of temperature	Within 0.	1% F.S./°C	Within 0.05	
Supply pressure fluctuation	Within 0.3%	F.S./0.01 MPa	_ N	ote 5)
Output flow Note 6)	80 L/min (/	ANR) or more (SUP = 0.14 MPa)	200 L/min (ANR) or more (SUP	= 0.4 MPa)
Air consumption Note 6)	5 L/min (ANR) or less (SUP = 0.14 MPa)		2 L/min (ANR) or less (SUP = 0.14 MPa)	, ,
All consumption	11 L/min (ANR) or	less (SUP = 0.4 MPa)	4 L/min (ANR) or less (SUP = 0.4 MPa)	(SUP = 0.4 MPa)
	General structure: -20 to 80°C			
Ambient and fluid	TIIS explosion-proof: -20 to 60°C			
temperature	ATEX intrinsically safe explosion-proof: —20 to 80°C (T5)  —20 to 60°C (T6)		ATEX intrinsically safe explosion-proof -20 to 80°C (T4/T5)	
·		O°C (16) C (T6)/-L type low-temperature specification	−20 to 60°C (T6)	
F	<u> </u>			
Explosion proof construction Note 7)		construction (Exd II BT5) of construction ( II 2G Ex ib II CT5/T6 Gb)	ATEX intrinsically safe explosion-proof construction (II 1G Ex ia II CT4/T5/T6 Ga)	
ATEX intrinsically safe explosion-proof	Ui ≤ 28 V, Ii ≤ 1	25 mA, Pi ≤ 1.2 W	Ui ≤ 28 V, Ii ≤ 10	0 mA, Pi ≤ 0.7 W
parameter (current circuit)	Ci ≤ 0 nF	, Li ≤ 0 mH	Ci ≤ 12.5 nF	, Li ≤ 1.5 mH
Exterior covering enclosure Note 8	)	JISF8007, IP65 (confo	rms to IEC Pub.60529)	
Transmission method Note 7		_	HART trai	nsmission
Air connection port Note 9		Rc 1/4 female thread, NPT 1/4 fe	emale thread, G 1/4 female threa	d
Electrical connection port Note 9	9	1/2 female thread, M20 x 1.5 fer	male thread, NPT 1/2 female thre	ad
Material/coating		Aluminum diecast body/baking t	finish with denatured epoxy resin	
Weight	2.4 kg (Without terminal be	ox)/2.6 kg (With terminal box)	2.6	kg
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Note 1) Specification values are given at normal temperature (20°C).

Note 2) 1/2 Split range (Standard). For operation with 1/2 split range, the linearity and

hysteresis should be 1% higher than the above specifications.

Note 3) Stroke adjustment: 0 to 60% 0 to 100°

Note 4) Characteristics relating to accuracy differ depending on combination with other constituent loop equipment, such as positioners and actuators.

Note 5) While there is no output changes due to pressure fluctuations, when the pressure supply setting is changed following calibration, once again adjust balance current and perform calibration.

Note 6) Air consumption is due to exhaust from nozzle. And (ANR) indicates JIS B0120 standard air.

Note 7) Model selection required for explosion proof construction and HART transmission. Note 8) For IP66 compliant products, refer to pages 142 to 145.

Note 9) Thread type can be specified by model selection.

# **Optional Specifications**

Type		IP8100-0□1-J/JR (Non-explosion proof)	IP8□01-0□2 (Non-explosion proof)	52-IP8□01-0□4	
		Electro-Pneumatic Positioner	Smart Positioner		
	Wiring		2-line		
	Output signal		4 to 20 mA DC		
Analog	Power supply voltage	12 to 35 V DC	10 to 28	3 V DC	
output	Load resistance	(Power supply voltage -12 V) ÷ 20 mA DC or less	0 to 750 Ω		
	Accuracy	±2% F.S. or less Note 1)	±0.5% F.S. or less Note 2)		
	Hysteresis	Within 1% F.S.	_		
	Wiring	_	2-line		
	Applicable standards	_	_	DIN19234/NAMUR Standard	
	Power supply voltage	_	10 to 28 V DC	5 to 28 V DC	
Alarm output 1, 2	Load resistance	_	10 to 40 mA DC	(Constant current output)	
output 1, 2	Alarm ON	_	R = 350 Ω ±10%	≥ 2.1 mA DC	
	Alarm OFF (Leakage current)	_	0.5 mA DC or less	≤ 1.2 mA DC	
	Response time	_	50 msec	or less	

Note 1) Indicates analog output accuracy with respect to actuator angle.

Note 2) Indicates analog output accuracy with respect to LCD display position value (P value).



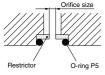
#### Accessory/Option

#### Pilot valve with output restriction (IP8000/8100)

In general, mounting on a small-size actuator may cause hunting. For prevention, a pilot valve with a built-in output restriction is available. The restriction is removable.

Actuator capacity	Orifice size	Part number	Pilot unit part number	Model selection accessory
90 cm <sup>3</sup>	ø0.7	P36801080	P565010-18	Α
180 cm <sup>3</sup>	ø1	P36801081	P565010-19	В

Note) Output orifice not required for Smart Positioner regardless of actuator capacity





Restrictor mounting diagram

Pilot valve bottom view

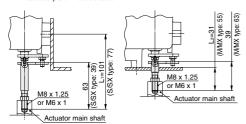
# Fork lever-type fittings (IP8100/8101)

2 kinds of rotary type IP8100/8101 fork lever-type fittings, that differ by installation dimensions dependent on bracket installation method, and 2 kinds of installation portion thread sizes, are available

When installing on the side surface, using fork lever assembly M provides interchangeability with the installation dimensions of SMC IP610 positioner. When installing on the rear surface, using fork lever assembly S also provides interchangeability with the installation dimensions of SMC IP610 positioner.

Part name	Unit number	Installation portion thread size	Model selection accessory
Fork lever assembly M	P368010-24	M8 x 1.25	С
Fork lever assembly S	P368010-25	IVIO X 1.25	D
Fork lever assembly MX	P368010-36	M6 x 1	C Note)
Fork lever assembly SX	P368010-37	IVIOXI	D Note)

Note) Installation portion thread size is M6 x 1 for IP8100-0□0-X14 when accessory C or D are selected.



Side mounting with the fork lever assembly M/MX

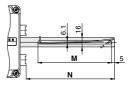
Rear mounting with the fork lever assembly S/SX

#### External feedback lever (IP8000/8001)

Different feedback levers are available dependent upon valve strokes. Order according to the valve stroke.

#### Feedback lever types

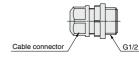
Stroke	Unit number		Size M	Cino N	Model selection
Stroke	IP8000	IP8001	SIZE IVI	Size IN	accessory
10 to 85 mm	P368010-20	P565010-323	125	150	Standard accessory
35 to 100 mm	P368010-21	P565010-324	110	195	E
50 to 140 mm	P368010-22	P565010-325	110	275	F
6 to 12 mm	P368010-260	P565010-329	75	75	Available as special order



#### Resin connector (Non-explosion proof specification)

Optional cable connectors are available for different cable sizes. These are not for explosion proof applications. Recommended for use with indoor applications.

Part name	Part number	Suited cable outer diameter
Resin-made cable clamp unit (A)	P368010-26	ø7 to ø9
Resin-made cable clamp unit (B)	P368010-27	ø9 to ø11



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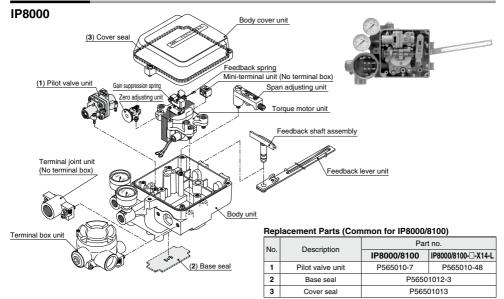
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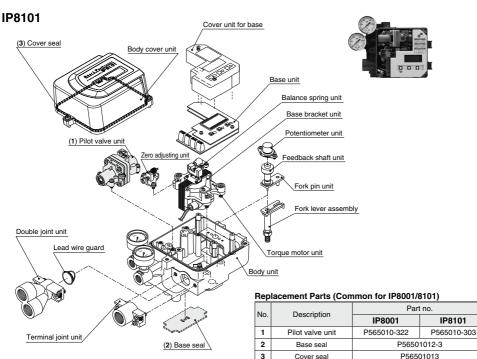
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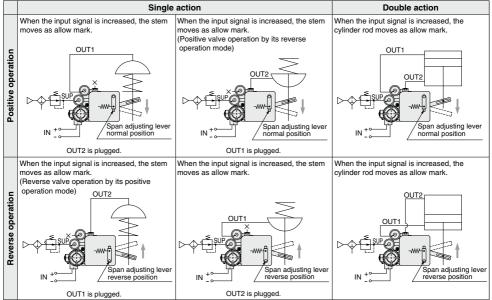
#### **Exploded View**



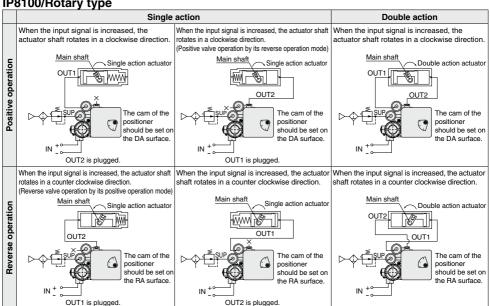


Piping Note) When the input signal is discontinued, the pressure of OUT1 decreases, and the pressure of OUT2 increases.

### IP8000/Lever type



# IP8100/Rotary type



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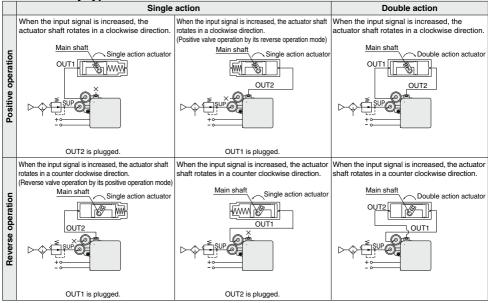


Piping Note) When the input signal is discontinued, the pressure of OUT1 decreases, and the pressure of OUT2 increases. Caution is also similarly required when changing the control direction in parameter mode.

#### IP8001/Lever type

	Single	action	Double action
	When the input signal is increased, the stem moves as allow mark.	When the input signal is increased, the stem moves as allow mark. (Positive valve operation by its reverse	When the input signal is increased, the cylinder rod moves as allow mark.
Positive operation	OUT1	operation mode)	OUT2 OUT2
	OUT2 is plugged.	OUT1 is plugged.	
	When the input signal is increased, the stem moves as allow mark. (Reverse valve operation by its positive	When the input signal is increased, the stem moves as allow mark.	When the input signal is increased, the cylinder rod moves as allow mark.
Reverse operation	operation mode) OUT2	OUT1  SUP OF THE PROPERTY OF T	OUT2 OUT1  SUP
	OUT1 is plugged.	OUT2 is plugged.	

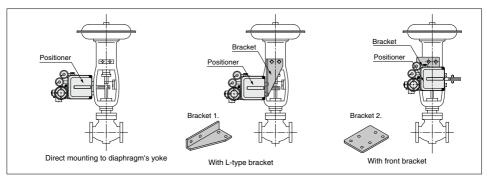
#### IP8101/Rotary type



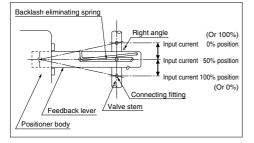
#### Installation

#### IP8000/8001 (Lever type)

1. Create brackets that are appropriate for the positioner and diaphragm valve mounting methods, and affix it firmly using the mounting hole on the side or rear surface.



2. The feedback lever that detects the displacement of valve stems should be mounted at a position so that the lever is at right angles to the valve stem for an input current of 50%. The figure is the configuration viewed from the front.



3. Brackets for lever type positioners, which are compliant with NAMUR and DIN/IEC 60534-6-1 are now available.

Part no.

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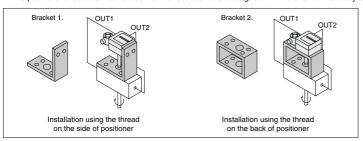
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Description

Bracket (NAMUR cor	mpliant) single unit	INI-224-	0-56
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8	55		
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2 × 10	20	<sub>20</sub> සි	4
'	20 70		
Bracket - (NAMUR compliant)	<u>-~+   -                                 </u>	INI-2	224-0-56
(			

## IP8100/8101 (Rotary type)

1. The positioner should be mounted so that the feedback shaft is aligned with the shaft of the rotary actuator.



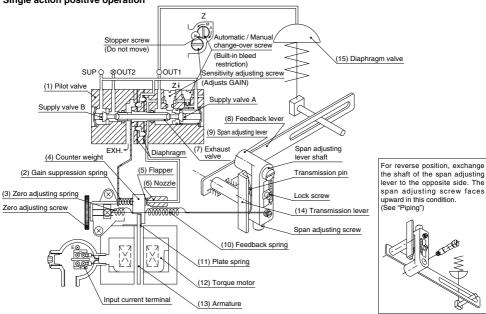


#### **Principle of Operation**

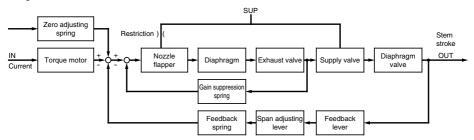
#### IP8000/Lever type

When the input current increases, (11) the plate spring of (12) the torque motor will work as a pivot, (13) armature will receive a counter clockwise torque, (4) the counter weight will be pushed to the left, the clearance between (6) the nozzle and (5) the flapper will increase, and the nozzle back pressure will decrease. Consequently, (7) the exhaust valve of (1) the pilot valve moves to the right, the output pressure of OUT1 increases and (15) the diaphragm moves downwards. The motion of (15) the diaphragm acts on (10) the feedback spring through (8) the feedback lever, (14) the transmission lever and (9) the span adjustment lever to rest at the balance position generated by the input current. (2) The gain suppression spring is for direct feedback of the motion of (7) the exhaust valve to (4) the counter weight to increase the stability of the loop. The zero point should be adjusted by change of (3) the zero adjustment spring tension.

#### Single action positive operation

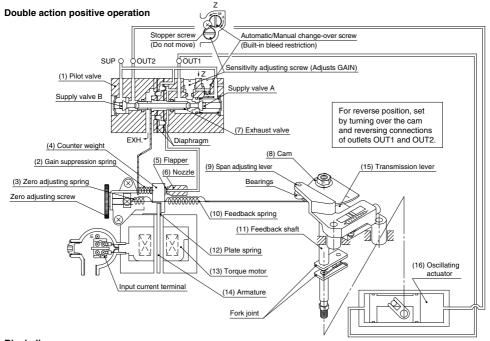


#### **Block diagram**

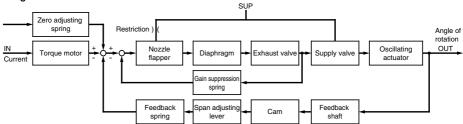


#### IP8100/Rotary type

When the input current increases, (12) the plate spring of (13) the torque motor will work as a pivot, (14) armature will receive a counter-clockwise torque, (4) the counter weight will be pushed to the left and the clearance between (6) the nozzle and (5) the flapper will increase, and the nozzle back pressure will decrease. Consequently, (7) the exhaust valve of (1) the pilot valve moves to the right, the output pressure of OUT1 increases that of OUT2 decreases and (16) the rotary actuator moves. The motion of (16) the actuator acts on (10) the feedback spring through (11) the feedback shaft, (8) the cam, (9) the span adjustment lever and (15) transmission lever to rest at the balance position generated by the input current. (8) the cam is set on the DA surface and operates positively while (16) the oscillating actuator shaft rotates in a clockwise direction when the input signal is increased. (2) The gain suppression spring is for direct feedback of the motion of (7) the exhaust valve to (4) the counter weight to increase the stability of the loop. The zero point should be adjusted by change of (3) the zero adjustment spring tension.



Block diagram



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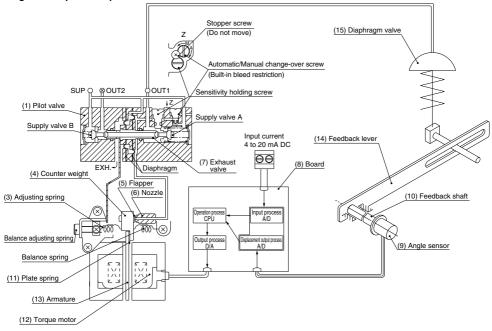


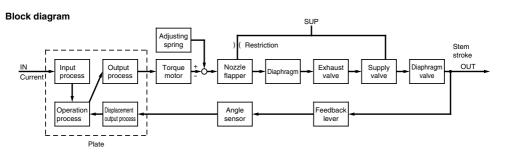
#### **Principle of Operation**

#### IP8001/Lever type

When the input current increases, the electrical current inside (12) the torque motor coil will change through (8) the plate's input process, operation process and output process, and (13) the armature will oscillate, with (11) the plate spring as its base. As a result, the clearance between (6) the nozzle and (5) the flapper will increase, and the nozzle back pressure will decrease. Consequently, (7) the exhaust valve of (1) the pilot valve moves to the right, the output pressure of OUT1 increases and causes (15) the diaphragm valve to move. The motion of (15) the diaphragm valve is transmitted to the displacement output process of (8) the board through (14) the feedback lever, (10) the feedback shaft and (9) angle sensor, and the calculated output position will match the input current.

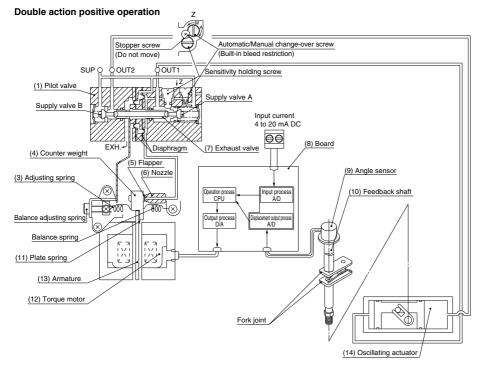
#### Single action positive operation

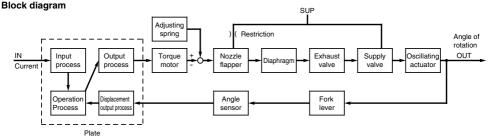




#### IP8101/Rotary type

When the input current increases, the electrical current inside (12) the torque motor coil will change through (8) the plate's input process, operation process and output process, and (13) the armature will oscillate, with (11) the plate spring as its base. As a result, the clearance between (6) the nozzle and (5) the flapper will increase, and the nozzle back pressure will decrease. Consequently, (7) the exhaust valve of (1) the pilot valve moves to the right, the output pressure of OUT1 increases and causes the output pressure of OUT2 to decrease, causing (14) the oscillating actuator to move. The motion of (14) the oscillating actuator is transmitted to the fork lever-type fitting, (10) the feedback shaft (9) angle sensor, and the displacement output process of (8) the board, and output position will match the input current.





IP IW 1301

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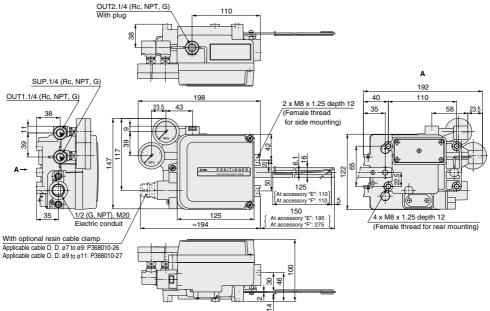
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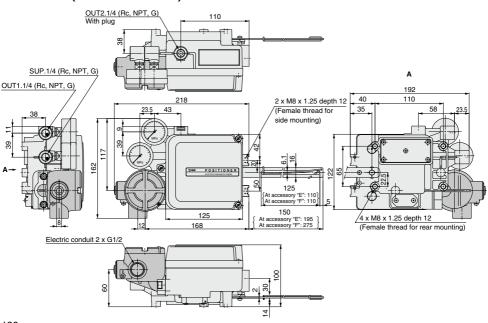
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# Dimensions/IP8000 (Lever type)

### IP8000-0□0 (Without terminal box)

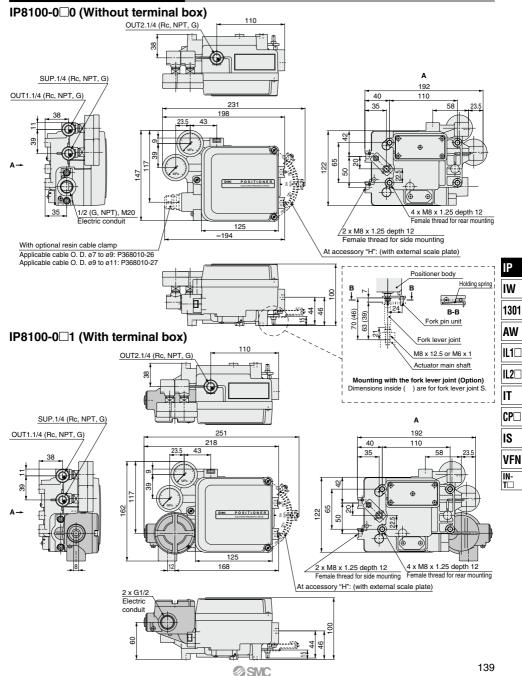


# IP8000-0□1 (With terminal box)

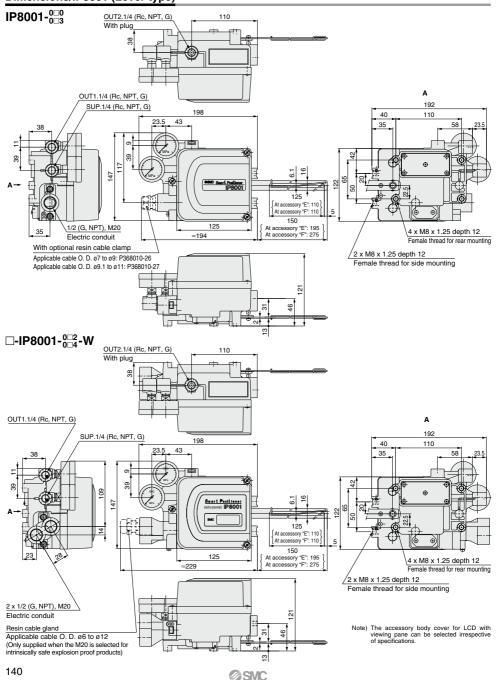


**SMC** 

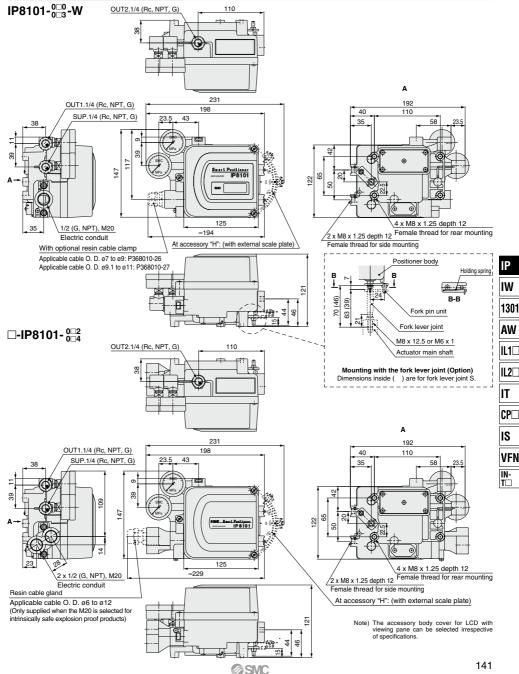
## Dimensions/IP8100 (Rotary type)



# Dimensions/IP8001 (Lever type)



## Dimensions/IP8101 (Rotary type)



# Electro-Pneumatic Positioner (Lever type/Rotary type)

# **Made to Order**

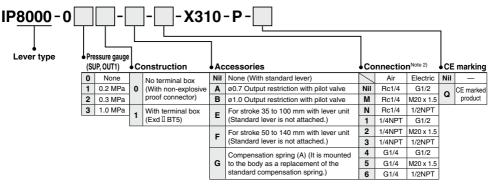
Please contact SMC for detailed dimensions, specifications and lead times.

### Water Resistant Type

# 1 Exterior Covering Enclosure: JISF8007 IP66 (Conforms to IEC60529)

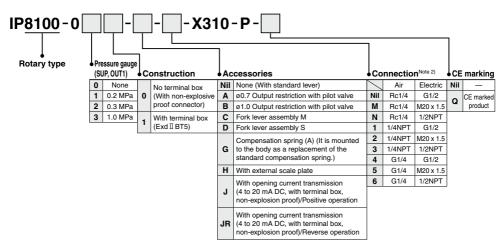
\* Same as the standard, other than the IP66 compliant protective cover.

How to Order IP8000/Lever type



Note 1) If two or more accessories are required, the part numbers should be given in alphabetical order. Note 2) If 1 is selected for Construction, M, N, 2, 3, 5, 6 cannot be selected for Connection.

#### IP8100/Rotary type



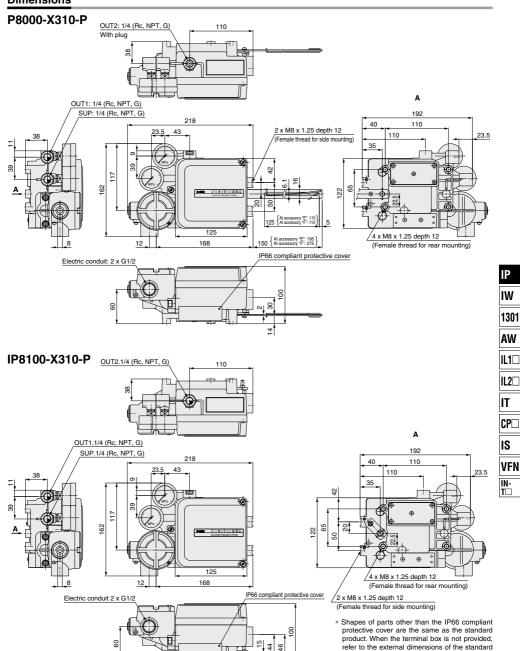
Note 1) If two or more accessories are required, the part numbers should be given in alphabetical order.

Note 2) Symbol J/JR is with terminal box, non-explosion proof specification. Select 1 for Construction.

Note 3) If 1 is selected for Construction, M, N, 2, 3, 5, 6 cannot be selected for Connection.



#### **Dimensions**



**SMC** 

product for dimensions and shapes of the

electric wiring parts.

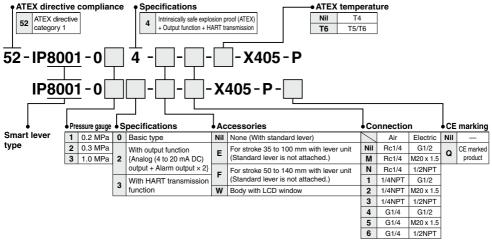


## Water Resistant Type

# 2 Exterior Covering Enclosure: JISF8007 IP66 (Conforms to IEC60529)

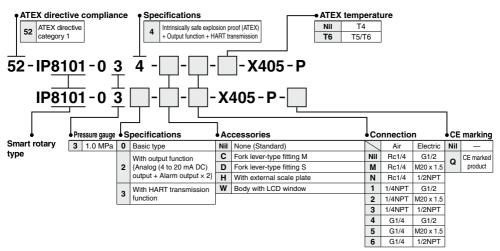
\* Same as the standard, other than the IP66 compliant protective cover.

# How to Order IP8001/Lever type



Note 1) If two or more accessories are required, the part numbers should be given in alphabetical order. Note 2) If a connecting port is  $M20 \times 1.5$ , a blue cable gland is included.

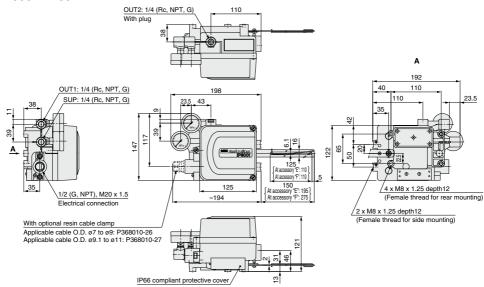
#### IP8101/Rotary type



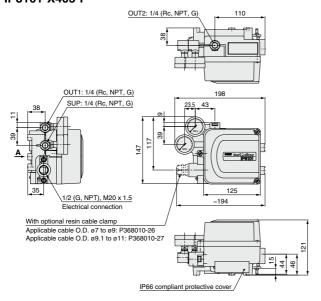
Note 1) If two or more accessories are required, the part numbers should be given in alphabetical order. Note 2) If a connecting port is M20 × 1.5, a blue cable gland is included.

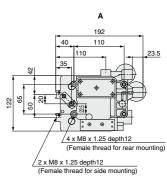
#### **Dimensions**

#### IP8001-X405-P



#### IP8101-X405-P





Shapes of parts other than the IP66 compliant protective cover are the same as the standard product. When the terminal box is not provided, refer to the external dimensions of the standard product for dimensions and shapes of the electric wiring parts. 1301 AW

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# **Technical data**

#### **Explosion proof**

#### 1. TIIS explosion-proof construction

The electro-pneumatic positioner IP8000/8100 becomes explosion proof, as certified by TIIS, according to the model selected. The explosion-proof grade has the following approval: Exd  $\scriptstyle\rm II$  BT5.

Take extra care when handling the positioner as explosion-proof equipment

#### To use as Exd II BT5

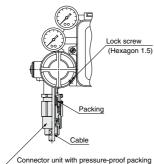
#### A) Pressure-proof packing

As shown below in the chart, use "Cable gland" (Option).

#### B) Metal piping

Attach the sealant fitting bracket near the cable port.

(For details, refer to "The guideline on electric equipment explosion proof" published by the Technology Institution of Industrial Safety).



#### Cable gland with pressure proof packing (Option)

Description	Unit product no.	Applicable outside diameter
Connector unit with	P368010-32	ø7.0 to ø10.0
pressure proof packing	P368010-33	ø10.1 to ø12.0

#### 2. ATEX Intrinsically safe explosion-proof construction

Pneumatic positioners IP8000/8100 and IP8001/8101 Smart Positioners are ATEX compliant, intrinsically safe and explosion proof, as certified by DEKRA, the accreditation body for explosion-proof products. Take extra care when handling these explosion-proof products.

In regards to explosion-proof grades,

The Pneumatic Positioner IP8 $\square$ 00 meets  $\mathbb{I}$ 2G Ex ib  $\mathbb{I}$  CT5/T6 Gb, and

The Smart Positioner IP8 $\square$ 01 meets the II 1G Ex ia II CT4/T5/T6 Ga. Check the positioner's specifications and explosion-proof grades and use in the most optimal environment.

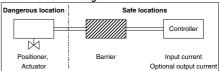
#### Wiring

When using the positioner as an intrinsically safe explosion-proof product, always set up a barrier in a **safe environment**, and perform each positioner's wiring through the barrier. Simultaneously, use the provided cable gland (M20 x 1.5) as the extension for the lead wire. If a connecting port other than M20 x 1.5 is selected, the cable gland will not be provided, so use a cable gland with the same or greater explosion-proof grades than this positioner.

#### Barrier

Connect the barrier as shown in the diagram below. Moreover, the user must select a barrier that is suitable for each function, based on the ATEX intrinsically safe explosionproof parameters (current circuit). For IP8001/8101 type smart positioners, use a linear resistant type barrier that is based on the explosion-proof parameters.

#### Barrier connection diagram



Moreover, at SMC, the barriers listed in the chart below are used to check operations. To purchase, please contact PEPPER + FUCHS Inc. (Germany).

#### Recommended barriers

	Manu-		No.	Applicable model	
	facturer	Model	Note	IP8□00-X14	52-IP8□01
For input signal (non HART transmission)	PEPPERL +	KFD2-CD-Ex1.32	_	0	0
For input signal (for HART transmission)		KFD2-SCD-Ex1.LK KCD2-SCD-Ex1	_	_	0
For analog output		KFD2-STC4-Ex1	_	_	0
	FUCHS (Germany)	KFD2-SOT2-Ex2	Transistor Output passive type	_	0
For alarm output		KFD2-ST2-Ex2	Transistor Output passive type	_	0
		KFD2-SR2-Ex2.W	Relay output	_	0

#### **HART transmission**

With smart positioners IP8001/8101, the user can operate the positioner using buttons and change parameter settings by viewing the LCD display (shown the right). Furthermore, depending on the model selected, the same button operation and parameter settings, and monitoring is possible from a remote location via HART transmission.



The table below lists an example of applications that are compatible with smart positioner IP8001/8101. Application selection must be made by the user. Please contact Emerson Process Management for further details.

#### HART transmission compatible application

Product name Note)	Manufacturer
AMS™ Suite : Intelligent Device Mar	nager ® Emerson Process
375/475 Field Communicator	Management (US)

Note) AMS™ Suite: Intelligent Device Manager® is a registered trademark of Emerson Electric Co.





# **Electro-Pneumatic Positioner/Smart Positioner** Specific Product Precautions 1

Be sure to read this before handling the products.

#### Operation

# **⚠** Warning

- 1. Do not operate the positioner outside the specified range as this may cause problems. (Refer to the specifications.)
- 2. Design the system to include a safety circuit to avoid the risk of danger should the positioner suffer failure.
- 3. Be sure that exterior lead-in wiring to the terminal box is based on the guidelines for explosion-protection of manufactory electric equipment when being used as a flame proof, explosion proof construction.
- 4. Do not remove terminal cover in a hazardous location while the power is on.
- 5. Covers for the terminal and body should be in place while operating.
- 6. When using as an intrinsically safe explosion-proof product, do not wire in a hazardous location while the power is on.

#### 

- 1. Do not touch the actuator or valve's oscillating section when supply pressure has been added, as this is dangerous.
- 2. Make sure fingers do not get caught when mounting and aligning the cam.

Cut off the pressure supply and always release the compressed air inside the positioner and actuator before performing this work.

- 3. Always use with the body cover unit mounted. Moreover, the positioner may not meet degrees of protection IP65 depending on the body cover mounting conditions. In order to meet degrees of protection IP65, tighten threads using the proper tightening torques (2.8 to 3.0 N·m).
- 4. Always flush the pipe's insides before piping to ensure foreign objects such as machining chips do not enter the positioner.
- 5. The actuator opening may become unstable when using the booster relay.
- 6. Always use a ground connection to prevent noise from the input current and to prevent damage because of static electricity.
- 7. Use the pressure reading on the supplied pressure gauge as an indication.
- 8. The supplied pressure gauge's needle will malfunction if the pressure supply to the internal mechanism or positioner freezes.

Ensure that the pressure gauge's internal parts do not freeze if using the pressure gauge in an operating environment with an ambient temperature of less than 0°C.

9. This positioner performs the fixed position control. Avoid turning ON or OFF the input signal highly frequently.

#### For Users

### 

1. Assemble, operate and maintain the positioners after reading the operation manual thoroughly and understanding the content.

#### Handling

# 

- 1. Avoid excessive vibration or impact to the positioner body and any excessive force to the armature, as these actions may cause damage to the product. Handle carefully while transporting and operating.
- 2. If being used in a place where vibration occurs, using a binding band is recommended to prevent broken wires because of the vibration.
- 3. When exposed to possible moisture invasion, please take the necessary measures. For example, if the positioner is left on-site for long periods, a plug should be put in the piping port and a body cover unit fitted to avoid water penetration.

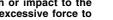
Take measures to avoid dew condensation inside the positioner if exposed to high temperature and humidity. Take enough measures against condensation especially when packing for export

4. Keep magnetic field off the positioner, as this affects its characteristics.

#### Air Supply

## **∕** Caution

- 1. As the positioner contains extra-fine orifices such as restrictor and nozzle, if drain or dust is present in the supply pressure line, malfunction (\*1) may result. In addition to an air filter (SMC Series AF), it is recommended to use a mist separator (SMC Series AM, AFM) and a micro mist separator (SMC Series AMD, AFD). Also, refer to "SMC Air Preparation System" for air quality.
- 2. Never use a lubricator, as this can cause a malfunction (\*1).
- 3. Do not use compressed air containing chemicals, organic solvents, salinity or corrosive gases, as this may cause malfunction.
- 4. When operating below the freezing point, protect the positioner from freezing.
- \*1 If the restrictor is clogged, output from the OUT1 port of the positioner may occur continuously or hunching and overshoot may occur.



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# Electro-Pneumatic Positioner/Smart Positioner Specific Product Precautions 2

Be sure to read this before handling the products.

#### **Operating Environment**

## **⚠** Caution

- Do not operate in locations with an atmosphere of corrosive gases, chemicals, sea water, or where these substances will adhere to the regulator.
- Do not operate out of the indicated operation temperature range as this may cause damage to electronic parts and seal materials to deteriorate.
- 3. Do not operate in locations where excessive vibration or impact occurs.
- 4. If the body cover is being installed in a place where the body cover is exposed to direct sunlight, the use of a standard body cover without the LCD window is recommended.

#### Maintenance

# **△** Warning

 After installation, repair or disassembly, connect compressed air and conduct tests to confirm appropriate function and leakage.

Do not use the positioner when noise from the bleeder sounds louder compared with the initial state, or when it does not operate normally. If these occur, check immediately if assembled and mounted correctly.

Never modify electrical construction to maintain explosion-proof construction.

# 

- 1. Confirm whether the compressed air is clean.
  - Dust, oil, or moisture mixed within the equipment may result in malfunction and positioner problems. Perform periodic inspection of the air preparation equipment to ensure clean air is always supplied.
- Improper handling of compressed air is dangerous. Not only observing the product specifications, but also replacement of elements and other maintenance activities should be conducted by personnel having sufficient knowledge and experience pertaining to instrumentation equipment.
- 3. Perform annual inspections of the positioner.

Replace badly damaged seals and units such as diaphragm and O-ring during the inspection.

When used in tough environmental and/or service conditions such as seaside locations, replacements should be undertaken more frequently.

#### Maintenance

# **∧** Caution

- 4. When performing inspections, demounting the positioner, or replacing the elements with the positioner still in its mounted position, first, stop the compressed air, then exhaust the residual pressure before undertaking operation.
- Should the restrictor become clogged with carbon particles, etc., demount automatic/ manual change-over screw (with built-in restrictor) and clean it using a Ø0.2 wire.
  - Stop the compressed air and remove the screw to switch the pilot valve off before replacing the restrictor.
- Apply just a small amount of grease set by SMC to the sliding parts (O-ring and exhaust valve) when disassembling a pilot valve unit. Replacing the valve unit every three years is recommended.
- 7. Check for air leakage from pipes that pass compressed air and connecting parts.

Air leakage from air piping results in reduced operational performance and a decline of characteristics, etc.

It is structurally necessary for air to be released from the bleeder, it is not abnormal as long as the air consumption is within the specified range.